

Solitons, Vortices, Instantons

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Solitons in a nutshell

- Solitons were first discovered in the 19th century as surface waves on water.
- Whereas usually localized waves change their shape due to dispersion, solitons do not.
- mathematically, solitons can appear in nonlinear diff. equations, the nonlinearity compensates the dispersion.
- Typical (integrable) examples for nonlinear equations where solitons appear are:
 - the KdV-equation $\partial_t \psi + \partial_x^3 \psi + 6\psi \partial_x \psi = 0$, e.g. in hydrodynamics
 - the nonlinear-Schrödinger equation $i\partial_t \psi + \partial_x^2 \psi \mp 2|\psi|^2 \psi = 0$, e.g. in waveguides
 - The sine-gordon equation, $\partial_x^2 \psi - \partial_t^2 \psi = \sin \psi$, e.g. in condensed matter

Recap: solitons in 1 + 1 dim space-time

In one of the previous talks, we were looking for nontrivial, stationary finite energy solutions (to the e.o.m.) in 1 + 1 dim. space-time with

$$\mathcal{L} = \frac{1}{2}(\partial\phi)^2 - \frac{\lambda}{4}(\phi^2 - v^2)^2,$$

(for a real, scalar field ϕ). The energy is

$$M = \int dx \left(\frac{1}{2} \left(\frac{d\phi}{dx} \right)^2 + \frac{\lambda}{4} (\phi^2 - v^2)^2 \right),$$

thus $\phi(r \rightarrow \infty) = \pm v$.

Trivial solutions are the vacua ($M = 0$):

$$\phi_{\pm}(x) = \phi_{\pm}(+\infty) = \phi_{\pm}(-\infty) = \pm v.$$

Recap: solitons in 1 + 1 dim space-time

We found the kink and antikink with $M \sim \mu v^2$ ($\mu^2 = \lambda v^2$), concentrated in a region $l \sim \frac{1}{\mu}$.

$$J_{top} := \frac{1}{2v} \epsilon^{\mu\nu} \partial_\nu \phi$$

leads to the conserved charge

$$Q_{top} = \int_{-\infty}^{+\infty} dx J_{top}^0(x) = \frac{1}{2v} (\phi(+\infty) - \phi(-\infty)) \in \mathbb{Z},$$

which implies that kink ($Q_{top} = 1$) and antikink ($Q_{top} = -1$) are stable with respect to the vacuum ($Q_{top} = 0$).

Intermezzo: topological mappings

The asymptotic condition,

$$\phi(r \rightarrow \infty) = \pm v,$$

can be described as a mapping of the 2-point-set $(-\infty, \infty)$ to the 2-point-set $(-v, v)$, which is equivalent to a mapping $S^0 \rightarrow S^0$.

Definition: Two continuous mappings g and f from X to Y (topological spaces) are *homotopic* if there exists a continuous function (*homotopy*) $H(t, x) : [0, 1] \times X \rightarrow Y$ with $H(0, x) = f(x)$ and $H(1, x) = g(x)$.

Intermezzo: topological mappings

In our cases we are always interested in mappings between spheres, i.e. $\phi_\infty : S^n \rightarrow S^n$ as spatial infinity in \mathbb{R}^n is topologically equivalent to $S^{(n-1)}$

It can be shown that for $n \geq 1$ such mappings can be characterized by an integer winding number ($n \in \mathbb{Z}$) which is called the Pontryagin index.

Consider for example $S^1 \rightarrow S^1$. The functions

$$f_{a,n}(\theta) = \exp i(n\theta + a) \quad \theta \in [0, 2\pi]$$

for fixed integer n and arbitrary a are homotopic with

$$H_{a,b,n}(t, \theta) = \exp i(n\theta + (1-t)a + tb).$$

2+1: Vortices

Consider a complex scalar field with

$$\mathcal{L} = \partial\phi^\dagger\partial\phi - \lambda \left(\phi^\dagger\phi - v^2\right)^2.$$

The Mass of a soliton would be

$$M = \int d^2x \left[\partial_i\phi^\dagger\partial_i\phi + \lambda \left(\phi^\dagger\phi - v^2\right)^2 \right].$$

Finiteness requires $|\phi| \rightarrow v$ at spatial infinity.
This suggests the ansatz $\phi(r \rightarrow \infty) = ve^{i\theta}$ in polar coordinates.

2+1: Vortices, the picture

Writing $\phi = \phi_1 + i\phi_2$ we see that
 $(\phi_1, \phi_2) \rightarrow v(\cos \theta, \sin \theta) = \frac{v}{r}(x, y)$.
 This vector points radially outwards.

Computing the gradient of the field,

$$\vec{\partial}\phi \rightarrow \frac{v}{r} \begin{pmatrix} \partial_x (x + iy) \\ \partial_y (x + iy) \end{pmatrix} = \frac{v}{r} \begin{pmatrix} 1 \\ -i \end{pmatrix}$$

leads to the current:

$$\vec{J} = i \left(\vec{\partial}\phi^\dagger \phi - \phi^\dagger \vec{\partial}\phi \right) \rightarrow \frac{v}{r} \begin{pmatrix} -2y \\ 2x \end{pmatrix}.$$

This is a vector of constant length, $2v$ whirling around at spatial infinity.

2+1: Vortices

Obviously ϕ maps $S^1 \rightarrow S^1$, thus we know the homotopy group to be \mathbb{Z} and vortices are topologically stable with respect to the vacuum. $[\phi]^n$ has the same properties and we identify n as the conserved charge (winding number).

Plugging the behavior of ϕ , i.e. $\phi \sim v$ and $\partial_i \phi \sim \frac{v}{r}$, into the expression for the energy yields:

$$M = \int d^2x \left[\partial_i \phi^\dagger \partial_i \phi + \lambda \left(\phi^\dagger \phi - v^2 \right)^2 \right] \sim v^2 \int d^2x \frac{1}{r^2}.$$

This is, of course, logarithmically divergent.

What can we do?

- consider vortex-antivortex pairs
- gauge the theory

2+1: Two vortices

Now consider a vortex and an antivortex (vortex with negative charge) at some (large) distance $R = R_1 - R_2$ ($R \gg a$ where a is the size of the vortex):

$$\varphi = \phi_+(r + R_2)\phi_-(r + R_1).$$

At infinity $\varphi \rightarrow v$ and $\partial\varphi \rightarrow 0$ thus M is finite.

Between R_1 and R_2 , we find $\varphi \sim v e^{2i\theta}$.

Now a very rough estimate of the energy is

$$M \sim v^2 \int d^2x \frac{1}{r^2} \sim v^2 \log \frac{R}{a}.$$

We have an attractive log potential (as in 2-dim. coulomb case). This configuration cannot be static, vortex and antivortex tend to annihilate and release energy.

2+1: Gauging for finite energy

We gauge the theory in the usual way by replacing $\partial_i\phi$ with $D_i\phi = \partial_i\phi - ieA_i\phi$. Then finite energy can be achieved by requiring

$$A_i(r \rightarrow \infty) \longrightarrow -\frac{i}{e} \frac{1}{|\phi|^2} \phi^\dagger \partial_i \phi = \frac{1}{e} n \partial_i \theta$$

where n is the winding number.

$$\Rightarrow D_i\phi \rightarrow \partial_i\phi - \frac{\phi^\dagger \partial_i \phi}{|\phi|^2} \phi = \partial_i\phi \left(1 - \frac{\phi^\dagger \phi}{|\phi|^2}\right) = 0$$

We can then also calculate the flux as

$$Flux \equiv \int d^2x B = \oint_C dx_i A_i = \frac{n}{e} \oint_C dx_i \frac{d}{dx_i} \theta = \frac{n2\pi}{e}.$$

This vortex appears as a flux tube in type II superconductors.

3+1: The hedgehog

In 3 + 1 dimensions we proceed as before. Spatial infinity now is S^2 , thus we consider scalar fields ϕ_a ($a = 1, 2, 3$), transforming as a vector $\vec{\phi}$ under $O(3)$ with the Lagrangian $\mathcal{L} = \frac{1}{2} \partial \vec{\phi} \cdot \partial \vec{\phi} - \lambda (\vec{\phi}^2 - v^2)^2$. The energy (time-independent) is then:

$$M = \int d^3x \left[\frac{1}{2} (\partial \vec{\phi})^2 + \lambda (\vec{\phi}^2 - v^2)^2 \right]$$

Again we have the requirement $|\vec{\phi}(r \rightarrow \infty)| \rightarrow v$, thus $\vec{\phi}(r = \infty)$ lives on S^2 . The obvious choice for our fields is now

$$\phi^a(r \rightarrow \infty) = v \frac{x^a}{r}.$$

Just like the vortex, this does not yet have finite energy, and we therefore gauge the theory, with an $O(3)$ -gauge-potential, A_μ^b .

3+1: The hedgehog, gauging for finite energy

So we replace $\partial_i \phi^a$ by

$$D_i \phi^a = \partial_i \phi^a + e \epsilon^{abc} A_i^b \phi^c$$

and choose A such that $D_i \phi^a$ vanishes at infinity:

$$A_i^b(r \rightarrow \infty) = \frac{1}{e} \epsilon^{bij} \frac{x^j}{r^2}$$

If we now consider a small lab at infinity, $\vec{\phi}$ points approximately in the same direction everywhere, $O(3)$ is broken down to $U(1)$.

The massless gauge field points radially outwards, it can be interpreted as the t'Hooft monopole, which we have learned about earlier.

Its mass has been calculated to be $\sim 137 M_W$

$(d) + (1) \leftrightarrow (d + 1)$: **The instanton as a soliton**

Let us now consider time-dependent configurations in d space and 1 time dimensions:

$$\mathcal{S} = \int d^d x dt [\mathcal{L}] = \int d^d x dt \left[\frac{1}{2} (\partial_t \phi)^2 - \frac{1}{2} (\vec{\partial} \phi)^2 - V(\phi) \right]$$

Upon performing a Wick rotation we get the Euclidian action:

$$\mathcal{S}_E = \int d^d x d\tau \left[\frac{1}{2} (\partial_t \phi)^2 + \frac{1}{2} (\vec{\partial} \phi)^2 + V(\phi) \right]$$

For the instanton we require $\mathcal{S}_E = \int d^{d+1} x \left[\frac{1}{2} \delta^{ab} \partial_a \phi \partial_b \phi + V(\phi) \right]$ to be finite.

For the solitons we had required $M = \int d^D x \left[\frac{1}{2} \delta^{ab} \partial_a \phi \partial_b \phi + V(\phi) \right]$ to be finite.

Obviously, for $d + 1 = D$ these conditions are equivalent!

Interpretation of the Instanton: Vacuum tunneling

Now we shall take a look at $0 + 1$ dim. space-time, i.e. ordinary (quantum) mechanics (if we identify ϕ with the coordinate x). Again consider a double-well potential

$$V(\phi) = (\phi^2 - v^2)^2 \quad \phi \text{ real, scalar.}$$

We know that for imaginary time we can have instanton solutions which are just the kinks from $1 + 1$ dim. space-time!

$$\mathcal{S}_{E,kink} = \int_{-\infty}^{+\infty} d\tau \left[\frac{1}{2} \left(\frac{\partial \phi_{kink}}{\partial \tau} \right)^2 + V(\phi_{kink}) \right] = \text{finite}$$

$$\langle -v | e^{-iHt} | v \rangle = \int [d\phi] e^{iS} \longrightarrow \langle -v | e^{-H\tau} | v \rangle = \int [d\phi] e^{-S_E} \neq 0$$

In euclidian space-time we have a finite transition amplitude between the vacua.

Interpretation of the Instanton: Vacuum tunneling

Classically, the ground state (vacuum) is either

$$|vac\rangle = |v\rangle \text{ or } |vac\rangle = | - v\rangle$$

Quantum mechanically the vacuum is

$$|vac\rangle = \frac{1}{\sqrt{2}} (|v\rangle + | - v\rangle),$$

due to tunneling.

This suggests we interpret the instanton as a tunneling process between different vacua.

Since in the path integral all paths are weighed with e^{-S_E} , configurations with finite action, i.e. instantons will dominate.

Instantons and gauge theory

Now, as the final part we consider an nonabelian gauge-theory without scalar fields in euclidian space.

$$\mathcal{S}_E(A) = \int d^4x \frac{1}{2g^2} \text{tr} F_{\mu\nu} F_{\mu\nu}$$

with $A_\mu = \frac{\tau^a}{2} A_\mu^a$, $F_{\mu\nu} = \partial_\mu A_\nu - \partial_\nu A_\mu + [A_\mu, A_\nu]$.

Under a gauge transformation U :

$$A'_\mu = U^{-1} A_\mu U + U^{-1} \partial_\mu U.$$

Obviously, finite action, i.e. an instanton, can be achieved by the pure gauge:

$$A(r \rightarrow \infty) = U^{-1} \partial_\mu U.$$

Instantons and gauge theory

Now, for $SU(2)$ we can write

$$U = \exp(i\vec{\epsilon} \cdot \vec{\tau}) = u_0 + i\vec{u} \cdot \vec{\tau},$$

with real u_0 and \vec{u} , that have to satisfy $u_0^2 + \vec{u}^2 = 1$ because U is unitary. Clearly this is the equation for S^3 (S^3 is the group manifold of $SU(2)$).

$$U : S^3(\text{infinity in euclid. spacetime}) \longrightarrow S^3$$

Now it can be shown that for a mapping $f : S^3 \rightarrow S^3$, $h_i := f^{-1}\partial_i f$ the winding number is:

$$n(S^3 \rightarrow S^3) = \frac{-1}{24\pi^2} \int d\theta_1 d\theta_2 d\theta_3 \text{tr} (\epsilon_{ijk} h_i h_j h_k) \in \mathbb{Z}$$

Instantons and gauge theory

With the definitions:

$$\tilde{F}_{\mu\nu} = \frac{1}{2}\epsilon_{\mu\nu\lambda\rho}F_{\lambda\rho} \quad \text{and} \quad K_\mu = 4\epsilon_{\mu\nu\lambda\rho}\text{tr} \left[A_\nu\partial_\lambda A_\rho + \frac{2}{3}a_\nu A_\lambda A_\rho \right]$$

we see that $\partial_\mu K_\mu = 2\text{tr} [F_{\mu\nu}\tilde{F}_{\mu\nu}]$.

In our case (pure gauge) $K_\mu = \frac{4}{3}\epsilon_{\mu\nu\lambda\rho}\text{tr} [A_\nu A_\lambda A_\rho]$.

$$\int d^4x \text{tr} [F_{\mu\nu}\tilde{F}_{\mu\nu}] = \frac{1}{2} \int d^4x \partial_\mu K_\mu = \frac{1}{2} \int_{S^3} d\sigma_\mu K_\mu = 16\pi^2 n$$

Now take a look at the axial-vector current: $\partial_\mu J_5^\mu = \frac{1}{(4\pi)^2}\epsilon_{\mu\nu\lambda\rho}\text{tr} [F_{\mu\nu}F_{\lambda\rho}]$

$$Q_5 = Q_R - Q_L = \int d^4x \frac{1}{(16\pi^2)}\epsilon_{\mu\nu\lambda\rho}\text{tr} [F_{\mu\nu}F_{\lambda\rho}] = n$$

Summary

- Kink(1+1 dim): Mechanical model, tunneling (instanton)
- Vortex(2+1 dim): Coulomb gas, flux tubes (gauge theory)
- Hedgehog(3+1 dim): Magnetic monopole
- Instanton(4 dim): Vacuum tunneling, chiral anomaly

Literatur

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