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## Exercises on Group Theory

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### –HOME EXERCISES–

#### H 9.1 Matrix Identities

(a) Prove the following matrix identities:

- $(AB)^T = B^T A^T$
- $\text{tr}[A, B] = 0$
- $(e^A)^T = e^{A^T} \quad (e^A)^\dagger = e^{A^\dagger}$
- $e^{UAU^{-1}} = Ue^AU^{-1}$
- If  $\lambda$  is an eigenvalue of  $A$  then  $e^\lambda$  is an eigenvalue of  $e^A$ .
- $\det e^A = e^{\text{tr} A}$

*Hint: Bring  $A$  to Jacobi form,  $UAU^{-1} = J$ , and write  $J$  as a sum of a diagonal and a nilpotent matrix which commute. What is the exponential of a diagonal and of a nilpotent matrix?*

(b) Show the *Baker–Campbell–Hausdorff* formula to second order,

$$e^A e^B = e^{A+B+\frac{1}{2}[A,B]+\mathcal{O}((A,B)^3)}.$$

#### H 9.2 Subalgebras

Consider a Lie group  $G$  with Lie algebra  $\mathfrak{g}$  and a subspace  $\mathfrak{h} \subset \mathfrak{g}$ . Show:

- If  $\mathfrak{h}$  is a closed subalgebra, i.e.  $h_1, h_2 \in \mathfrak{h} \Rightarrow [h_1, h_2] \in \mathfrak{h}$ , then  $H = e^{\mathfrak{h}}$  is a subgroup of  $G$ .
- If  $\mathfrak{h}$  is an invariant subalgebra, i.e.  $h \in \mathfrak{h}, g \in \mathfrak{g} \Rightarrow [h, g] \in \mathfrak{h}$ , then  $H$  is a normal subgroup in  $G$ .
- If  $\mathfrak{h}$  is a null space, i.e.  $h \in \mathfrak{h}, g \in \mathfrak{g} \Rightarrow [h, g] = 0$ , then  $H$  is in the center of  $G$ .

### H 9.3 Algebraic equivalence of $SO(3)$ and $SU(2)$ , part 2

(a) Prove the formula

$$e^{i\vec{m}\cdot\vec{\sigma}} = \mathbb{1} \cos(m) + i \sin(m) \hat{m} \cdot \vec{\sigma}$$

with  $m = |\vec{m}|$ ,  $\hat{m} = \vec{m}/m$ . ( $\sigma_i$ : Pauli matrices,  $m_i \in \mathbb{R}$ )

(b) We write

$$SU(2) \ni U = e^{i\varphi\hat{n}\cdot\sigma/2}$$

with  $|\hat{n}| = 1$ . Choosing  $\hat{n}$  to be in the whole unit sphere, what is the parameter space of  $\varphi$ ? What is the identification at the boundary?

(c) For  $O \in SO(3)$  we have  $O = e^{\alpha\hat{n}\cdot\vec{L}}$  with  $0 \leq \alpha \leq \pi$  and  $\hat{n}$  again in the unit sphere  $S^2$  (see last sheet). Show that the map  $\mu : (\varphi, \hat{n}) \mapsto (\alpha = \varphi \bmod \pi, \hat{n})$  is a group homomorphism from  $SU(2)$  to  $SO(3)$ . What is the group element associated to  $\mu(\varphi = \pi, \hat{n})$ ? What is the preimage of  $(\alpha, \hat{n})$  in terms of  $SU(2)$  elements?

Since each  $O \in SO(3)$  has exactly two preimages, we find that  $SO(3) \cong SU(2)/\mathbb{Z}_2$  with  $\mathbb{Z}_2 = \{\pm \mathbb{1}_2\}$ . This fits nicely with the geometrical picture since the three-dimensional ball with opposite points at the boundary identified can be viewed as a three-sphere with opposite points identified. This space is also called *real projective space*,  $\mathbb{P}\mathbb{R}^3 = S^3/\mathbb{Z}_2$ .

### H 9.4 Negative definite Killing form

Show that if the Killing form on a matrix Lie algebra  $\mathfrak{g}$  is negative definite, i.e.  $\langle X, X \rangle < 0$  for all  $0 \neq X \in \mathfrak{g}$ , then the Lie group  $G = e^{\mathfrak{g}}$  is bounded.

### H 9.5 $U(n)$ decomposition

Remember that the Lie algebra of  $U(n)$  consists of the Hermitean  $n \times n$  matrices. Find a one-dimensional null space  $\mathfrak{h} \subset \mathfrak{su}(n)$ . Identify the associated subgroup of  $U(n)$ . This shows that  $U(n)$  is not semi-simple.

### H 9.6 Adjoint representation

Consider a Lie algebra  $\mathfrak{g}$  with basis  $T_i$  and structure constants  $[T_i, T_j] = f_{ijk}T_k$ . Show that the *adjoint representation*, defined by

$$\text{ad}(T_i)_{jk} = f_{ijk}$$

is a representation. What is its dimension?